

Approximate Bayesian inference
through the lens of large
deviations

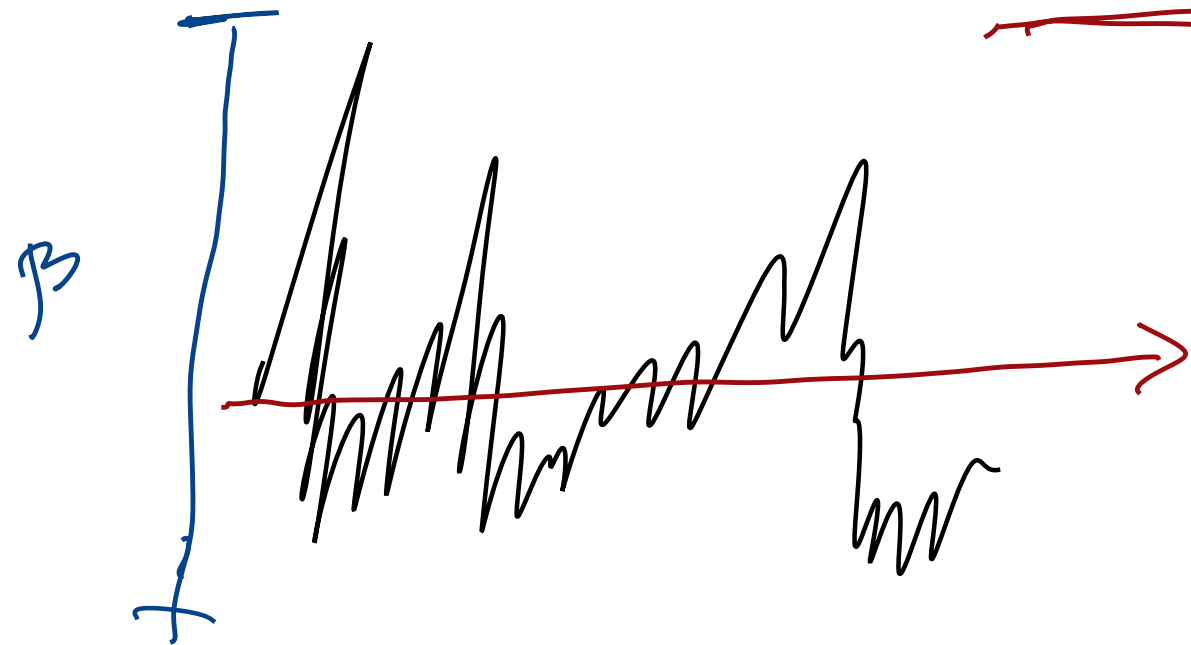
One part technical discussion

One part "where do we go

next?"

$$dX_t = \underline{f(X_t)dt} + \underline{\beta} dW_t$$

Ito
SDE

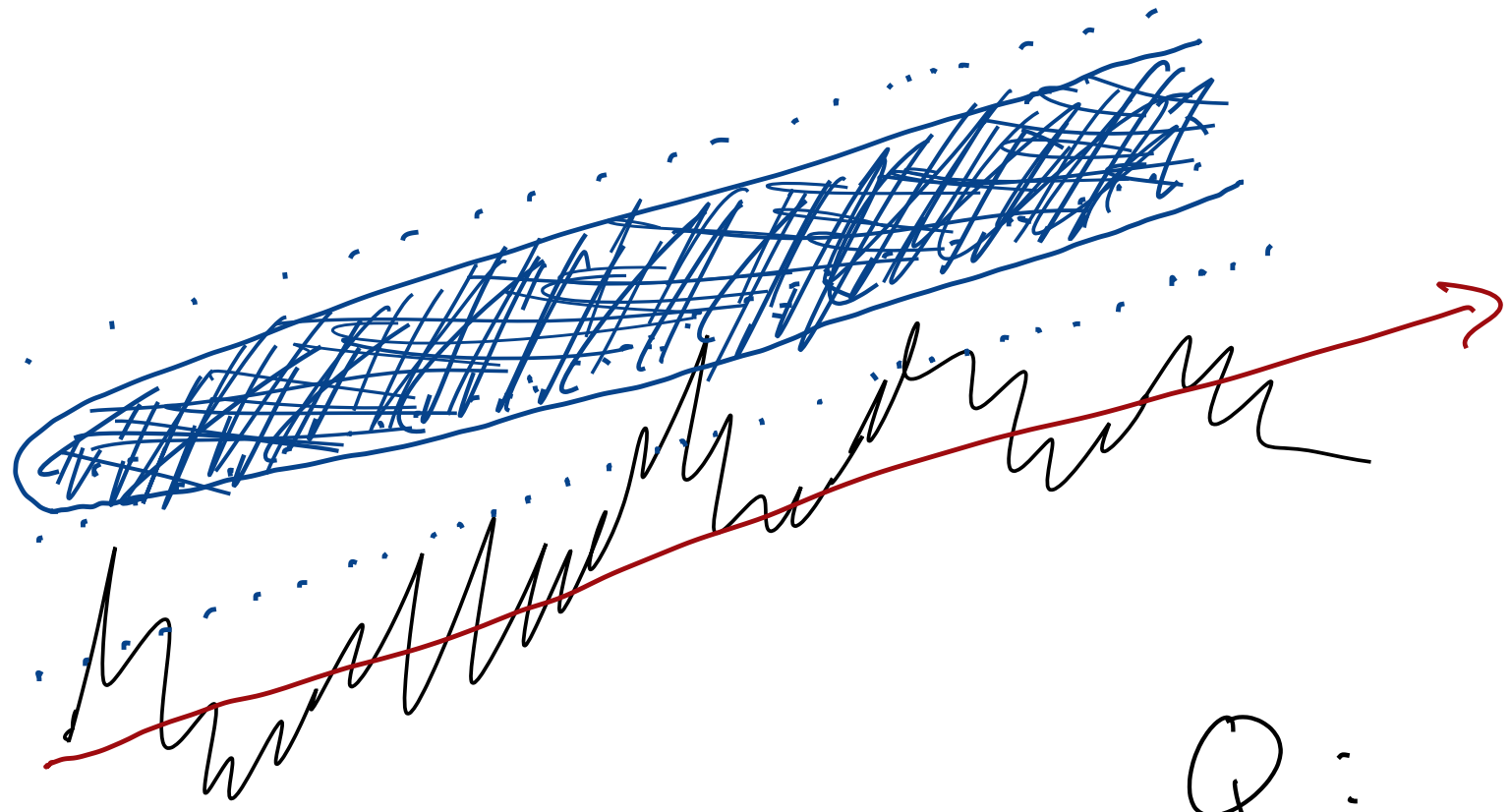


$$\int_0^T f(X_t) dt$$

↓
Rough
paths

$$dX_t = f(X_t) dt + \beta(X_t) dY_t$$

time \uparrow
MAP
time \downarrow



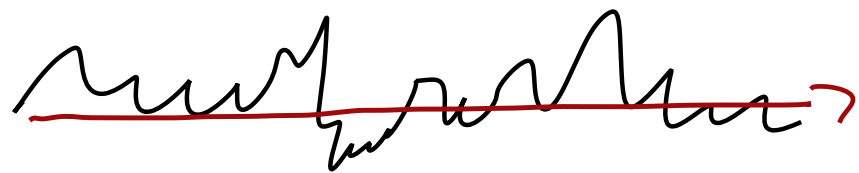
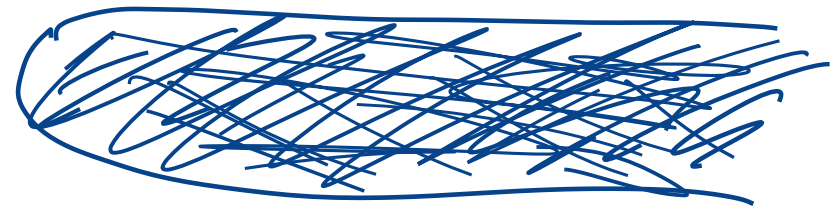
Q: What is
 $P(x_t \in A)$

$\sim e^{-C|x - m|^2}$

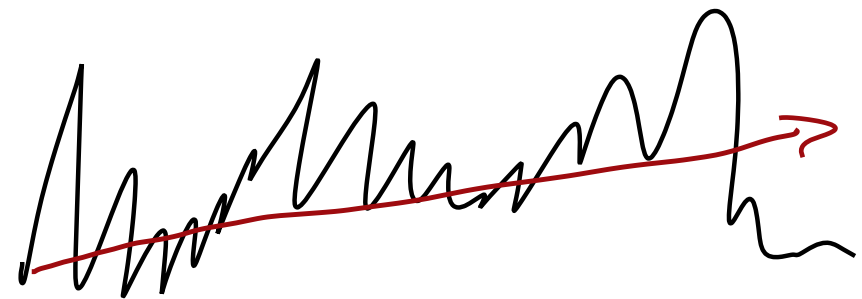
A (intuitive) :

- how large is β
- how far away is A

for small β and/or
 far away A , $P \approx \emptyset$.



$\beta \ll 1$



Formalise:

$$P \sim e^{-\frac{1}{\beta} I(A)}$$

$P(x_t \in A)$ depends on

• dist • $|x|$

inf $A = \mathbb{R}$

$$e^{-\frac{1}{\beta} \| \bar{F} - m \|_T^2}$$

Norm on the path space
(of W_t)

$$\left(\int_0^T \dot{x}_t^2 dt \right)^{1/2}$$

$$\langle a, a \rangle$$

$$= \|a\|^2$$

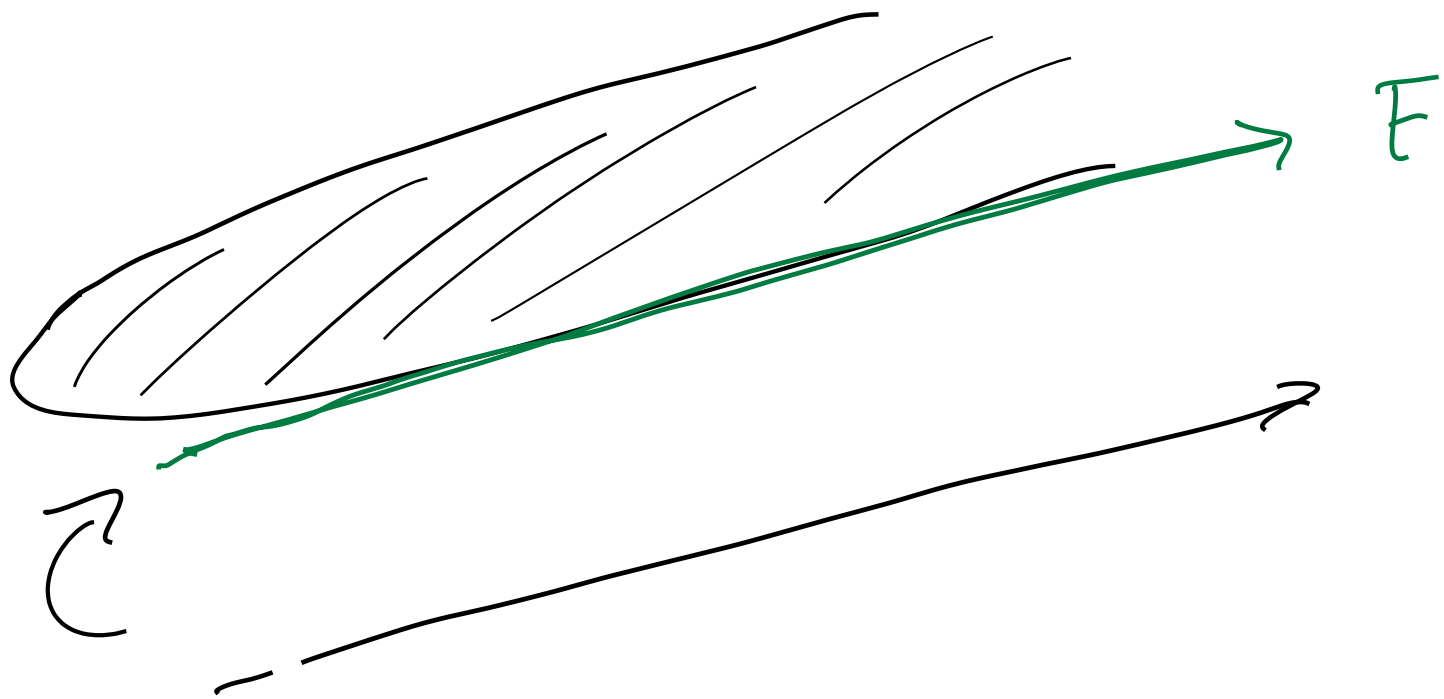
$$a \cdot a =$$

$$\|a\|^2 = a^2$$

$$\|x_T\|_T^2 = \int_0^T \dot{x}_t^2 dt$$

Cameron - Martin then
 \implies

$$I(x_t) = \int_0^T (\dot{x}_t - \dot{m}_t)^2 dt$$



$$I(F) =$$

$$\int_0^T (\dot{F}_t - \dot{m}_t)^2 dt$$

$$P(X_t \in A) \sim e^{-c_p I(\inf A)}$$

$$c_p \rightarrow \infty \text{ as } p \rightarrow \infty \quad e^{-\infty I(\inf A)}$$

$$I = \emptyset$$

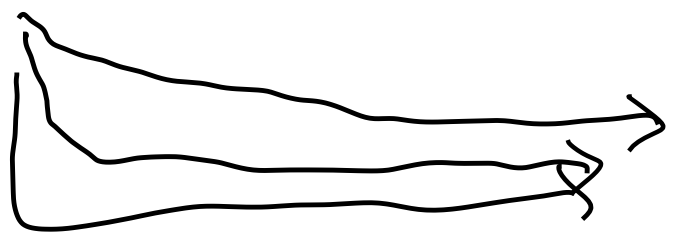
$$P(X_t \in F) + P(X_t \in F+k) + P(X_t \in F+2k) + \dots$$

$$e^{-\infty \cdot \emptyset}$$

$$e^{-C I(F)} + e^{-C I(F+k)} + \dots$$

$$= 1 = 1$$

Scap.



Unlikely events happen in
the least unlikely unlikely way

- F H Olander

2.5 other

examples of

hDPs

Let

Start with

• x a ~~microstate~~

• $M(x) =$ a ~~microstate~~

• $\arg \max_k P(M(x)) =$

an eq. state

• $N =$ system size.

Thermus

Thermodynamics

as $n \rightarrow \infty$

the system

goes to eq state

Thermo.
limit

\Rightarrow

fluctuations

away

from

min $I \rightarrow \emptyset$

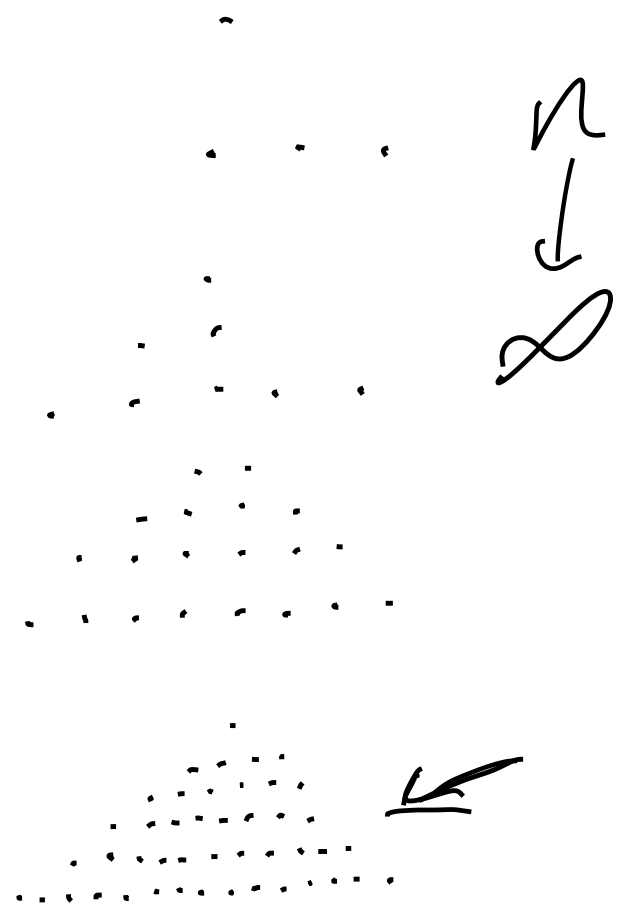
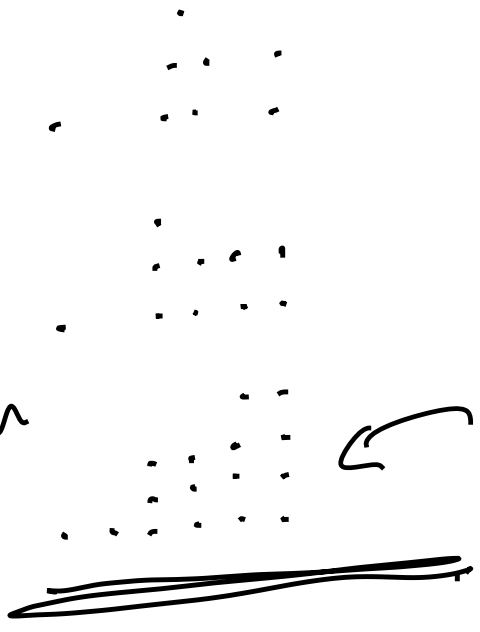
\Rightarrow

Thermo

satisfies

a hdp

Exp
whitely
when
measure
is
Gaussian



Another example :

as $n \rightarrow \infty$

emp. distn Converges
to the stationary meas.

$$D_{KL} (P_{emp} || p) \rightarrow 0$$

$n \rightarrow \infty$

Sarason's theorem

Lemma: Janov's theorem holds on
the path space.

ensemble of sample paths

Remark

$C([0, T], \mathbb{R}^2)$ as

is a
Polish
space

$N \rightarrow \infty$

$D_{KL}(P(\gamma)_{\text{emp}} \parallel P(\gamma))$

\implies

max
con
nvergence



Further remark:

The space of geometric



rough paths for any

Hölder exp. is Politi



\Rightarrow Can prove Sano's thm

$$C^{\alpha}_g (-)$$

Main theorem

Remark:

whole
convo-
will be
valid
for

Streat.

given
an
app.

correction
term.

Start in 2 ways

$t \mapsto X_t$

$t \mapsto Y_t$

~~W~~

~~M~~

- families of RV indexed
by time

- driven by an Ito SDE

in state-dependent
diffusion
coeff.

Max cost \Rightarrow the stats. of
sample paths tend towards the
ensemble P

If the sample paths themselves
are constrained by some cost

\Rightarrow the cost is reflected
in $P(\text{sample})$

Intertwinement
of 2 limits

So as $n \rightarrow \infty$ for fixed β ,
Sanov's thm $\Rightarrow -\log p = \frac{1}{\beta} V$
to first order in β

and $n \rightarrow \infty$ with $\beta \rightarrow 0 \Rightarrow$
 $p \rightarrow \delta_{p.l.a.}(x_t)$

\Rightarrow Sanov's thm produces state-wise LDPs

(which we know!

$$p = \max_{D_{KL}} = e^{-\frac{1}{\beta} V},$$

which satisfies an LDP)

Freidlin-
Wentzell
ag

Natural cost on sample paths:

= speed
proc.

↓

$$\begin{aligned}
 \frac{-\log p(x_t)}{G_t} &= C_p \int_0^T (\ddot{x}_t - \partial_t \mathbb{E} x_t)^2 dt && := C_p \|w\|_2^2 \\
 \frac{-\log q(y_t)}{G_t} &= C_p \int_0^T (\ddot{y}_t - \partial_t \mathbb{E} y_t)^2 dt && := C_p \|v\|_2^2
 \end{aligned}$$

• set an additional cost

$$\mathbb{E}_p x_t = o(\mathbb{E}_q y_t)$$

Then as $\beta \rightarrow 0$ path of
least is synchronisation

But recall: this

requires sampler under

COA

$\min(DK \tau_T)$

Main
Result

Statement based on
interview:

min FE T to find
the path stats

min h to get synched.

Fün